# Raport 1. Multipoint Reduction Approach for Non-Affine Right Hand Side Problems 

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## 1 Introduction

Standard global multipoint model order reduction, enhanced by the error estimator tool [1] for finite element method problems is performed on the system of equations of the following form:

$$
\begin{equation*}
\left(\boldsymbol{\Gamma}+s \mathbf{G}+s^{2} \mathbf{C}\right) \mathbf{E}(s)=s \mathbf{B I} \tag{1}
\end{equation*}
$$

where:

$$
\begin{equation*}
\mathbf{B}=c \widetilde{\mathbf{B}} /\left(Z_{P}^{1 / 2}\right) \tag{2}
\end{equation*}
$$

The approach [1] requires, that the right hand side of (1) - matrix $\widetilde{\mathbf{B}}$ is constant, while the port impedance $\left(Z_{P}\right)$ depends on $s$. Therefore, approach [1] can be applied in the analysis of the structures excited through f.e. homogeneous waveguide ports or coaxial lines. In the case of micro-strip lines and inhomogeneous ports one has to derive a novel error-estimator, which takes into account, that the matrix $\widetilde{\mathbf{B}}$ is frequency dependent (non-affine).

The goal of this report is to derive the multipoint reduction formulation for problems, with nonaffine RHS.

## 2 Standard error estimator (for affine RHS)

The goal-oriented error estimator is based on a residual error and is defined as follows:

$$
\begin{equation*}
E_{s}(s)=\max _{i}\left\{\eta_{i} \cdot\left(\mathbf{b}_{i}\right)^{T} \cdot\left(\mathbf{r}_{i}(s)\right) /\left|2 s \eta_{i}\left(\mathbf{b}_{i}\right)^{T} \cdot \mathbf{b}_{i}\right|\right\} \tag{3}
\end{equation*}
$$

where $\mathbf{r}_{i}$ is the i-th residual vector and $\mathbf{b}_{i}$ is the i-th vector of the matrix $\widetilde{\mathbf{B}}$. See [1] for details, eq. (24) and (25) - for slow and fast computation of an a-posteriori estimator, respectively. If the structure is excited by means of a single-mode, single-port, eq. (3) is simplified to:

$$
\begin{equation*}
E_{s}(s)=\max \left\{\eta \cdot(\mathbf{b})^{T} \cdot(\mathbf{r}(s)) /\left|2 s \eta(\mathbf{b})^{T} \cdot \mathbf{b}\right|\right\} \tag{4}
\end{equation*}
$$

## 3 Error estimator (for non-affine RHS)

In the following parts of the rep. we assume, that the structure is excited by means of a single-port and single-mode. If the excitation exhibits non-affine nature (which means that $\mathbf{b}$ depends on $s$ ), one can express $\mathbf{b}(s)$ as a linear combination of few $(N)$ vectors, since the field pattern at the ports is in general not strongly-dispersive:

$$
\begin{equation*}
\mathbf{b}(s) \approx \sum_{j=1}^{N} a_{j}(s) \cdot \mathbf{b}_{j} \tag{5}
\end{equation*}
$$

Note, that in order to obtain coefficients $a_{j}(s)$ and vectors $\mathbf{b}_{j}$ one has to perform the Proper Orthogonal Decomposition (POD) or Reduced Basis Method (RBM) for the whole frequency band. Let us also denote $\mathbf{b}_{R}=\left\{\mathbf{b}_{1} \mathbf{b}_{2} \ldots \mathbf{b}_{N}\right\}$ and $\mathbf{a}_{R}(s)=\left\{a_{1}(s) a_{2}(s) \ldots a_{N}(s)\right\}$ :

$$
\begin{equation*}
\mathbf{b}(s) \approx \mathbf{b}_{R} \cdot \mathbf{a}_{R}(s) \tag{6}
\end{equation*}
$$

In effect, the frequency dependence is pushed to the scalar functions $a(s)$ and the equation-to-bereduced exhibits affine nature.

Substituting (5) to (4) yields:

$$
\begin{array}{r}
E(s)=\max \left\{\eta \cdot(\mathbf{b}(\mathbf{s}))^{T} \cdot(\mathbf{r}(s)) /\left|2 s \eta(\mathbf{b}(\mathbf{s}))^{T} \cdot \mathbf{b}(\mathbf{s})\right|\right\} \approx \\
\approx \max \left\{\eta \cdot\left(\sum_{j=1}^{N} a_{j}(s) \cdot \mathbf{b}_{j}\right)^{T} \cdot(\mathbf{r}(s))\right. \\
\left./\left|2 s \eta\left(\sum_{j=1}^{N} a_{j}(s) \cdot \mathbf{b}_{j}\right)^{T} \cdot \sum_{j=1}^{N} a_{j}(s) \cdot \mathbf{b}_{j}\right|\right\}= \\
=\max \left\{\eta \cdot \mathbf{a}_{R}(s)^{T} \cdot\left(\mathbf{b}_{R}^{T} \cdot \mathbf{r}(s)\right)\right. \\
\left./\left|2 s \eta \cdot \mathbf{a}_{R}(s)^{T} \cdot\left(\mathbf{b}_{R}^{T} \cdot \mathbf{b}_{R}\right) \cdot \mathbf{a}_{R}(s)\right|\right\} . \tag{7}
\end{array}
$$

Finally, the fast formula for the error estimator can be derived, taking into account that the residual vector is defined as follows:

$$
\begin{array}{r}
\mathbf{r}(s)=2 s \mathbf{b}(s)- \\
\boldsymbol{\Gamma} \cdot \mathbf{Q} \cdot \mathbf{e}_{r}- \\
s \mathbf{G} \cdot \mathbf{Q} \cdot \mathbf{e}_{r}- \\
s \mathbf{b}(s) \cdot \mathbf{b}(s)^{T} \cdot \mathbf{Q} \cdot \mathbf{e}_{r}- \\
s^{2} \mathbf{C} \cdot \mathbf{Q} \cdot \mathbf{e}_{r}, \tag{8}
\end{array}
$$

where $\mathbf{e}_{r}$ denotes $N$ vectors of unknowns obtained from the reduced model:

$$
\begin{equation*}
\left(\widehat{\boldsymbol{\Gamma}}+s \widehat{\mathbf{G}}+s^{2} \widehat{\mathbf{C}}\right) \mathbf{e}_{r}(s)=s\left(\widehat{\mathbf{b}}_{R} \cdot \mathbf{a}_{R}(s)\right) \cdot \mathbf{I} \tag{9}
\end{equation*}
$$

Substituting (6) to (8) yields:

$$
\begin{array}{r}
\mathbf{r}(s)=2 s\left(\mathbf{b}_{R} \cdot \mathbf{a}_{R}(s)\right)- \\
\boldsymbol{\Gamma} \cdot \mathbf{Q} \cdot \mathbf{e}_{r}- \\
s \mathbf{G} \cdot \mathbf{Q} \cdot \mathbf{e}_{r}- \\
s\left(\mathbf{b}_{R} \cdot \mathbf{a}_{R}(s)\right) \cdot\left(\mathbf{b}_{R} \cdot \mathbf{a}_{R}(s)\right)^{T} \cdot \mathbf{Q} \cdot \mathbf{e}_{r}- \\
s^{2} \mathbf{C} \cdot \mathbf{Q} \cdot \mathbf{e}_{r} . \tag{10}
\end{array}
$$

Finally, the fast estimator formula reads:

$$
\begin{array}{r}
E_{f a s t}(s)=\max \left\{\eta \cdot \mathbf{a}_{R}(s)^{T} \cdot\left(\mathbf{b}_{R}^{T} \cdot \mathbf{r}(s)\right)\right. \\
\left./\left|2 s \eta \cdot \mathbf{a}_{R}(s)^{T} \cdot\left(\mathbf{b}_{R}^{T} \cdot \mathbf{b}_{R}\right) \cdot \mathbf{a}_{R}(s)\right|\right\}= \\
\max \left\{\eta \cdot \left(2 s \mathbf{a}_{R}(s)^{T} \cdot\left(\mathbf{b}_{R}^{T} \cdot \mathbf{b}_{R}\right) \cdot \mathbf{a}_{R}(s)-\right.\right. \\
\mathbf{a}_{R}(s)^{T} \cdot\left(\mathbf{b}_{R}^{T} \cdot \mathbf{\Gamma} \cdot \mathbf{Q}\right) \cdot \mathbf{e}_{r}- \\
s \mathbf{a}_{R}(s)^{T} \cdot\left(\mathbf{b}_{R}^{T} \cdot \mathbf{G} \cdot \mathbf{Q}\right) \cdot \mathbf{e}_{r}- \\
s \mathbf{a}_{R}(s)^{T} \cdot\left(\mathbf{b}_{R}^{T} \cdot\left(\mathbf{b}_{R} \cdot \mathbf{a}_{R}(s)\right) \cdot\left(\mathbf{b}_{R} \cdot \mathbf{a}_{R}(s)\right)^{T} \mathbf{Q}\right) \cdot \mathbf{e}_{r}- \\
\left.s^{2} \mathbf{a}_{R}(s)^{T} \cdot\left(\mathbf{b}_{R}^{T} \cdot \mathbf{C} \cdot \mathbf{Q}\right) \cdot \mathbf{e}_{r}\right) \\
\left./\left|2 s \eta \cdot \mathbf{a}_{R}(s)^{T} \cdot\left(\mathbf{b}_{R}^{T} \cdot \mathbf{b}_{R}\right) \cdot \mathbf{a}_{R}(s)\right|\right\} \tag{11}
\end{array}
$$

## 4 Numerical tests

In the numerical test the three structures have been taken into account (Fig. 1).


Figure 1: Structures: a) filter, b) coupler, c) Vivaldi antenna.


Figure 2: Filter plots.

|  | Filter | Coupler | Antenna |
| :---: | :---: | :---: | :---: |
| Number of Frequency point | 300 | 100 | 101 |
| Frequency bandwidth | $2-12 \mathrm{GHz}$ | $0.6-2.4 \mathrm{GHz}$ | $4-6 \mathrm{GHz}$ |
| Number of expanding points | 4 | 1 | 3 |
| Number of vectors in V | 54 | 36 | 21 |
| Speedup | 19.8 | 10.8 | 26 |
| Reduction time | 83.3 s | 23.4 s | 108.94 s |



Figure 3: Coupler plots.

## References

[1] Rewienski, Michal, Adam Lamecki, and Michal Mrozowski. "Greedy multipoint model-order reduction technique for fast computation of scattering parameters of electromagnetic systems." IEEE Transactions on Microwave Theory and Techniques 64.6 (2016): 1681-1693.


Figure 4: Antenna plots.

